CS4740
CLOUD COMPUTING

Two-Phase Commit

Prof. Chang Lou, UVA CS, Spring 2024
LAB 2A IS RELEASED

— Lab2A: Raft - Leader Election
  — Deadline: 3/12 23:59:59 EST
  — A lot of interesting questions to answer in your lab 2A implementation
    — How can a group of votes decide the unique leader? What if the old leader dies? What if some network failures happen? How to send RPCs to multiple nodes in parallel?...

— My advice (again): Start the lab 2A immediately
  — Don't wait for lectures: they only cover high-level designs
  — You'll learn much more from paper and hands-on experience
  — Tomorrow: OLSSON HALL 009, Lab 2A Overview Session, 5:00 PM. We strongly suggest you to attend.
  — In summary: start lab 2 today!
We discussed two types of agreements:
- Atomic commitment: e.g., when to meet
- Consensus: e.g., which zoom link to use

Why we need such agreements in DS?
- Atomic commitment $\leq$ Scalability: sharding
- Consensus $\leq$ Fault tolerance: replication

Today we discuss a solution 2PC for atomic commitment:
- We have discussed transactions in single-node settings
- Let's discuss how distributed transactions are implemented
OUTLINE

— Context
— Two-phase commit (2PC)
— 2PC failure scenarios
— 2PC limitations
EXAMPLE: WEB SERVICE ARCHITECTURE

- Web front end (FE), database server (DB), network. FE is stateless, all state in DB.
- Suppose the FE implements a banking application (supporting account transfers, listings, and other functionality).
- Suppose the DB supports ACID transactions and the FE uses transactions.

Question: How do we make this:
- scalable?
- fault tolerant?
SCALABILITY: SHARDING

— FE and DB are both sharded:
  — FEs accept requests from end-users’ browsers and process them concurrently.
  — DB is sharded, say by user IDs.
— Suppose each DB backend is on its own transactional (ACID). Then, FE issues transactions against one or more DB shards.
– FE is stateless, so the fact that it is shared means it’s also replicated/fault tolerant.

– But DB is stateful, so active replication is needed for each shard. Each shard is managed by a replica group, which cooperate to keep themselves up to date with respect to the updates.

– FE sends requests for DB different shards go to different replica groups.
- Question: What are the challenges of implementing ACID across the entire sharded & replicated, DB service?
— Ignore replication. Implementing ACID across all DB shard servers:

— Case 1: No transactions ever span multiple shards. Easy: individual DB shard performs transaction.

— Case 2: Transactions can span multiple shards. Challenge: shards participating on any transaction need to agree on (1) whether or not to commit a transaction and (2) when to release the locks.
CHALLENGES DUE TO SHARDING

— Example:
  — Say FE service is a banking service that supports the TRANSFER and REPORT_SUM functions from the previous lecture.
  — If the two accounts are stored on different shards, then the two operations (deduct from one and add to the other) will need to be executed either both or neither.
  — Unfortunately, the two machines can fail, or decide to unilaterally abort, INDEPENDENTLY.
Example:

So, you need an agreement protocol, and in this case the most suitable is an atomic commitment protocol (why?).

Well-known atomic commitment protocol: two-phase commit.
CHALLENGES DUE TO REPLICATION

- Ignore sharding. Implementing ACID across all replicas of a given shard:
  - Challenge: All replicas of the shard must execute all operations in the same order.
  - If the operations are deterministic, then agreeing on the order of keeps the copies of the database on the different replicas will evolve identically, i.e., they will all be kept consistent.
CHALLENGES DUE TO REPLICATION

Example

- Suppose there are two transactions, each with a single operation, against the same cell in the database:
  - TX1: x += 1
  - TX2: x *= 2

- Internally, all three replicas are ACID databases, so they will serialize these transactions, e.g., either (TX1, TX2) OR (TX2, TX1).

- If Replica A processes (TX1, TX2) and Replica B processes (TX2, TX1), then after executing these transactions, the DB copies on the two replicas will diverge to x=8 and x=7, respectively.
CHALLENGES DUE TO REPLICAATION

Example

– The problem of agreement on the order in which to execute operations can be cast as an instance of the consensus problem (why?).
– Well known consensus protocol: Paxos, Raft
– We study these protocols next time.
Two-Phase Commit (2PC)
send_money(A, B, amount) {
  Begin_Transaction();
  if (A.balance - amount >= 0) {
    A.balance = A.balance - amount;
    B.balance = B.balance + amount;
    Commit_Transaction();
  } else {
    Abort_Transaction();
  }
}
SINGLE-SERVER: ACID

— **Atomicity**: all parts of the transaction execute or none (A’s decreases and B’s balance increases)

— **Consistency**: the transaction only commits if it preserves invariants (A’s balance never goes below 0)

— **Isolation**: the transaction executes as if it executed by itself (even if C is accessing A’s account, that will not interfere with this transaction)

— **Durability**: the transaction’s effects are not lost after it executes (updates to the balances will remain forever)
DISTRIBUTED TRANSACTIONS?

- Partition databases across multiple machines for scalability (A and B might not share a server)

- A transaction might touch more than one partition

- How do we guarantee that all of the partitions commit the transactions or none commit the transactions?
TWO-PHASE COMMIT (2PC)

— **Goal**: General purpose, distributed agreement on some action, with failures
  — Different entities play different roles in the action

— **Running example**: Transfer money from A to B
  — Debit at A, credit at B, tell the client “okay”
  — Require both banks to do it, or neither
  — Require that one bank never act alone

— This is an **all-or-nothing** atomic commit protocol
STRAW MAN PROTOCOL

1. C → TC: “go!”
STRAW MAN PROTOCOL

1. C -> TC: “go!”
2. TC -> A: “debit $20!”
   ▶ TC -> B: “credit $20!”
   ▶ TC -> C: “okay

   A, B perform actions on receipt of messages
REASONING ABOUT THE STRAW MAN PROTOCOL

— What could possibly go wrong?
— 1. Not enough money in A’s bank account?
— 2. B’s bank account no longer exists?
— 3. A or B crashes before receiving message?
— 4. The best-effort network to B fails?
— 5. TC crashes after it sends debit to A but before sending to B?
SAFETY VERSUS LIVENESS

— Note that TC, A, and B each have a notion of committing
— We want two properties:

— 1. Safety
   — If one commits, no one aborts
   — If one aborts, no one commits

— 2. Liveness
   — If no failures and A and B can commit, action commits
   — If failures, reach a conclusion ASAP
A CORRECT ATOMIC COMMIT PROTOCOL

1. C -> TC: “go!”

Client C

Transaction Coordinator TC

Bank A

Bank B
A CORRECT ATOMIC COMMIT PROTOCOL

- 1. C -> TC: “go!”
- 2. TC -> A, B: “prepare!”
A CORRECT ATOMIC COMMIT PROTOCOL

1. C -> TC: “go!”
2. TC -> A, B: “prepare!”
3. A, B -> P: “yes” or “no”
A CORRECT ATOMIC COMMIT PROTOCOL

1. C -> TC: “go!”
2. TC -> A, B: “prepare!”
3. A, B -> P: “yes” or “no”
4. TC -> A, B: “commit!” or “abort!”
   - TC sends commit if both say yes
   - TC sends abort if either say no
A CORRECT ATOMIC COMMIT PROTOCOL

1. C -> TC: “go!”
2. TC -> A, B: “prepare!”
3. A, B -> P: “yes” or “no”
4. TC -> A, B: “commit!” or “abort!”
   - TC sends commit if both say yes
   - TC sends abort if either say no
5. TC -> C: “okay” or “failed”

— A, B commit on receipt of commit message
REASONING ABOUT ATOMIC COMMIT

— Why is this correct?
  — Neither can commit unless both agreed to commit

— What about performance?
  — 1. Timeout: I’m up, but didn’t receive a message I expected
    — Maybe other node crashed, maybe network broken
  — 2. Reboot: Node crashed, is rebooting, must clean up
TIMEOUTS IN ATOMIC COMMIT

— Where do hosts wait for messages?
— 1. TC waits for “yes” or “no” from A and B
   — TC hasn’t yet sent any commit messages, so can safely abort after a timeout
   — But this is conservative: might be network problem
     — We’ve preserved correctness, sacrificed performance
— 2. A and B wait for “commit” or “abort” from TC
   — If it sent a no, it can safely abort (why?)
   — If it sent a yes, can it unilaterally abort?
   — Can it unilaterally commit?
   — A, B could wait forever, but there is an alternative…
Consider Server B (Server A case is symmetric) waiting for commit or abort from TC
  Assume B voted yes (else, unilateral abort possible)
B -> A: “status?” A then replies back to B. Four cases:
  (No reply from A): no decision, B waits for TC
  Server A received commit or abort from TC: Agree with the TC’s decision
  Server A hasn’t voted yet or voted no: both abort
    TC can’t have decided to commit
  Server A voted yes: both must wait for the TC
    TC decided to commit if both replies received
    TC decided to abort if it timed out
What are the liveness and safety properties?
- Safety: if servers don’t crash, all processes will reach the same decision
- Liveness: if failures are eventually repaired, then every participant will eventually reach a decision

Can resolve some timeout situations with guaranteed correctness

Sometimes however A and B must block
- Due to failure of the TC or network to the TC

But what will happen if TC, A, or B crash and reboot?
HOW TO HANDLE CRASH AND REBOOT?

— Can’t back out of commit if already decided
  — TC crashes just after sending “commit!”
  — A or B crash just after sending “yes”
— If all nodes knew their state before crash, we could use the termination protocol…
  — Use write-ahead log to record “commit!” and “yes” to disk
RECOVERY PROTOCOL WITH NON-VOLATILE STATE

— If everyone rebooted and is reachable, TC can just check for commit record on disk and resend action
— TC: If no commit record on disk, abort
  — You didn’t send any “commit!” messages
— A, B: If no yes record on disk, abort
  — You didn’t vote “yes” so TC couldn’t have committed
— A, B: If yes record on disk, execute termination protocol
  — This might block
TWO-PHASE COMMIT

— This recovery protocol with non-volatile logging is called Two-Phase Commit (2PC)

— Safety: All hosts that decide reach the same decision
  — No commit unless everyone says “yes”

— Liveness: If no failures and all say “yes” then commit
  — But if failures then 2PC might block
    — TC must be up to decide

— Doesn’t tolerate faults well: must wait for repair
2PC Failure Scenarios
RULE

— Take a try, get one cookie

— Get it right, win an extra cookie for your pal!
WHAT IF PARTICIPANT FAILS BEFORE SENDING RESPONSE?
WHAT IF PARTICIPANT FAILS BEFORE SENDING RESPONSE?
WHAT IF PARTICIPANT FAILS AFTER SENDING VOTE
WHAT IF PARTICIPANT FAILS AFTER SENDING VOTE
WHAT IF PARTICIPANT LOST A VOTE?
WHAT IF PARTICIPANT LOST A VOTE?
WHAT IF COORDINATOR FAILS BEFORE SENDING PREPARE?
WHAT IF COORDINATOR FAILS BEFORE SENDING PREPARE?
WHAT IF COORDINATOR FAILS AFTER SENDING PREPARE?
WHAT IF COORDINATOR FAILS AFTER SENDING PREPARE?
WHAT IF COORDINATOR FAILS AFTER RECEIVING VOTES
WHAT IF COORDINATOR FAILS AFTER RECEIVING VOTES
WHAT IF COORDINATOR FAILS AFTER SENDING DECISION?
WHAT IF COORDINATOR FAILS AFTER SENDING DECISION?
WHAT IF COORDINATOR FAILS AFTER SENDING ONLY ONE DECISION?
WHAT IF COORDINATOR FAILS AFTER SENDING ONLY ONE DECISION?
WHAT IF COORDINATOR FAILS BEFORE SENDING ANY DECISION?
WHAT IF COORDINATOR FAILS BEFORE SENDING ANY DECISION?
2PC Limitations
2PC IS BLOCKING

— A process can block indefinitely in its uncertainty period until a TC or network failure is resolved.
— If TC is also a participant, then a single-site failure can cause 2PC to block indefinitely!
— And it blocks while each shard server is holding locks, preventing other transactions that don’t even interact with the failed shard server from making progress!
— This is why 2PC is called a blocking protocol and cannot be used as a basis for fault tolerance.
2PC IS EXPENSIVE

— Time complexity: 3 message latencies on the critical path: PREPARE → PREPARE-OK/FAIL → ABORT/COMMIT.

— Message complexity: common case for n participants + 1 TC: 3n messages.

— That’s expensive, esp. if shards are geo distributed.

— Optimizations, or adding an extra phase (3PC), cannot address the blocking/performance problems of 2PC while maintaining its semantic.
TAKEAWAYS

– How to construct our fuller Web service architecture from Lecture 1 (took us long, ha)?
  – today: how to achieve scalability through sharding, with 2PC.
  – future: how to achieve fault tolerance through replication.

– Next class: Azure Guest Talk
ACKNOWLEDGEMENT

THIS COURSE IS DEVELOPED HEAVILY BASED ON COURSE MATERIALS SHARED BY PROF. INDRANIL GUPTA, PROF. ROBERT MORRIS, PROF. MICHAEL FREEDMAN, PROF. KYLE JAMIESON, PROF. WYATT LLOYD AND PROF. ROXANA GEAMBASU. MANY APPRECIATIONS FOR GENEROUSLY SHARING THEIR MATERIALS AND TEACHING INSIGHTS.